

# Numerical Integration and Ordinary Differential Equations.

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# Numerical Integration(Quadrature)

Numerical evaluation of the integral  $\int f(x)dx$  is called quadrature. Most often, integrand  $f(x)$  is quite complicated and it may not be possible to carry out the integration analytically.

In such cases, we resort to numerical integration.

However we can only evaluate definite integrals, i.e.,  $\int_a^b f(x) dx$ .

Matlab provides the following built in functions for numerical integration.

1. *quad* integrates a specified function over specified limits, based on adaptive *Simpson's rule*.

## Definition

In numerical analysis, *Simpson's rule* is a method for numerical integration, the numerical approximation of definite

integrals. Specifically, it is the following approximation: 
$$\int_a^b f(x) dx \approx \frac{b-a}{6} \left( f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right)$$

2. *quadl* ( the last letter is an ell, as in QUADL, not 1) integrates a specified function over specified limits, based on adaptive *Lobatto quadrature*. This one is more accurate than quad but it also uses more function evaluations.

## Definition

A quadrature formula of highest algebraic degree of accuracy for the interval  $[a,b]=[-1,1]$  and weight  $p(x)=1$  with two fixed nodes: the end-points of  $[-1,1]$ . The *Lobatto quadrature* formula has the form

$$\int_a^b f(x) dx = A[f(-1) + f(1)] + \sum_{j=1}^n C_j f(x_j).$$

The general call syntax for both `quad` and `quad1` is as follows:

$$Integral = quad('your - function', a, b, tol, trace, p1, p2, )$$

To use `quad1`, you just replace `quad` in the syntax. As shown in the syntax, both functions require you to supply the integrand as a user-written function.

The optional input argument `tol` specifies absolute tolerance (the default value is  $10^{-6}$ ).

A nonzero value of the other optional argument, `trace`, shows some intermediate calculations at each step. The optional arguments `p1`, `p2` etc., are simply passed on to the user-defined function as input arguments in addition to `x`.

**Example:1** Compute  $\int_{1/2}^{3/2} e^{-x^2} dx$ .

The simplest syntax:

```
function y = erf cousine(x);
y = e-x2;
y = quad ('erf cousine',1/2,3/2)
y =
    0.3949.
```

# Double integration:

To evaluate integral of the form

$$\int_{x_{min}}^{x_{max}} \int_{y_{min}}^{y_{max}} f(x, y) dy dx.$$

MATLAB provides a function *dblquad*. The calling syntax for *dblquad* is

$$I = \text{dblquad}(f_{xy} - fun, x_{min}, x_{max}, y_{min}, y_{max}, tol, @method).$$

Where *tol* and *method* are optional input arguments. The optional argument *tol* Specifies tolerance (default is 10<sup>-6</sup>), as previously discussed for 1-D integration, and *method* specifies a choice that the user makes about the method of integration to be used, e.g., *quad* or *quad1*. The default method is *quad*. The user-defined integrand function, *f<sub>xy</sub> - fun*, must be written such that it can accept a vector *x* and a scalar *y* while evaluating the integrand.

Example:2

Compute  $\int_{-1}^1 \int_0^2 (1 - 6x^2y) dy dx$ .

The simplest syntax:

```
function y = erf(x);  
y = 1 - 6x2y;  
y = dblquad ('erf', -1, 1, 0, 2)  
y =  
    4.0000.
```

# Ordinary Differential Equations

There is a separate suite of ordinary differential equation solvers in MATLAB. Long ago, MATLAB used to have just two built-in functions for solution of ODEs-ode23 and ode45.

The syntax of use of ode23 is

$$[time, solution] = ode23(your - function, tspan, x_0)$$

## Example:3

Solve the first-order linear differential equation  $\frac{dx}{dt} = x + t$  with the initial condition  $x(0) = 0$ .

The simplest syntax:

```
function xdot = simpode(t, x);  
    xdot = x + t;  
    tspan = [0 2];  
    x0 = 0;  
    [t,x] = ode23 ('simpode', tspan, x0)  
    plot (t, x);  
    xlabel( ' t ' );  
    ylabel( ' x ' );
```